

Supplementary Materials for “Incorporating Minimum Variances into Weighted Optimality Criteria”

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1 Approximate $c_{\mathcal{E}}$ -Optimal CRDs

An approximate CRD is represented by its proportional replication vector \mathbf{p}_d where $p_{di} \in [0, 1]$ such that $\sum_i p_{di} = 1$. To ensure estimability of all contrasts, we must have $p_{di} \in (0, 1)$. If the traditional c -optimal design for a contrast has p_{di} in this range, obviously it will also be $c_{\mathcal{E}}$ -optimal. Otherwise, at least one $p_{di} = 0$. If all non-zero p_{di} of the traditional c -optimal design were reduced by an arbitrarily small amount, ϵ , that is redispersed among the zero p_{di} , the resulting approximate design would have the desired estimability. However, decreasing ϵ will always lead to a decrease in the targeted contrast’s variance, so there can be no $c_{\mathcal{E}}$ -optimal design. To reconcile this issue, we propose a hybrid approach between the exact and approximate design theory.

Note, we can refer to an approximate CRD’s replication vector as $\mathbf{r}_d = N\mathbf{p}_d$ which places the exact and approximate design approaches on a similar scale. If $N\mathbf{p}_d$ is comprised of integers, the approximate design is equivalent to an exact design. Just like in the exact

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design case, we ensure estimability of all contrasts by requiring $r_{di} \geq 1$. In the approximate case, we have $r_{di} \in [1, N - t + 1]$. The approximate $c_{\mathcal{E}}$ -optimal design is the set of such r_{di} that minimize

$$\sum_i \frac{h_i^2}{r_{di}} + \lambda \left(\sum_i j r_{di} - 1 - N + t \right). \quad (1)$$

Let $2 \leq t_h \leq t$ be the number of treatments with nonzero coefficients in the desired contrast $\mathbf{h}^T \boldsymbol{\tau}$. The approximate $c_{\mathcal{E}}$ -optimal design then has

$$r_{di}^* = \begin{cases} 1 & \text{if } h_i = 0 \\ (N - t + t_h) \frac{|h_i|}{\sum_i j |h_i|} & \text{otherwise .} \end{cases} \quad (2)$$

2 Proof of Theorem 1

By induction The $c_{\mathcal{E}}$ -criterion minimizes $\text{Var}(\widehat{\mathbf{h}^T \boldsymbol{\tau}}) = \sum_i \frac{h_i^2}{r_{i,N}}$ subject to $r_{di} \geq 1$ to ensure estimability. The base case has $N = t$ so $r_{di,N} = 1$. Thus, for d_{N+1}^* , there is an \tilde{i} such that $r_{\tilde{i},N+1} = r_{\tilde{i},N} + 1$, otherwise estimability no longer holds. Now suppose d_N^* is a $c_{\mathcal{E}}$ -optimal exact design with $N > t$ runs. The $c_{\mathcal{E}}$ -optimal design for $N + 1$ runs, d_{N+1}^* , must have a treatment \tilde{i} where $r_{\tilde{i},N+1} \geq 1 + r_{\tilde{i},N}$, otherwise $\sum_i r_{\tilde{i},N+1} < N + 1$. This gives us two cases to consider.

Case 1: $r_{\tilde{i},N+1} = r_{\tilde{i},N} + 1$. We now show this forces $r_{i,N+1} = r_{i,N}$ for all $i \neq \tilde{i}$. Clearly $\sum_{i \neq \tilde{i}} r_{i,N+1} = \sum_{i \neq \tilde{i}} r_{i,N} = N - r_{\tilde{i},N}$, implying both d_N^* and d_{N+1}^* minimize $\sum_{i \neq \tilde{i}} \frac{h_i^2}{r_{i,N}}$ given the sum equality constraints. The two designs therefore assign the same replication numbers to all treatments except \tilde{i} up to permutation among the $r_{i,N}$ with the same value for h_i^2 .

Case 2: $r_{\tilde{i},N+1} = r_{\tilde{i},N} + a$ for an integer $a \geq 2$. Then $\sum_{i \neq \tilde{i}} r_{i,N+1} = \sum_{i \neq \tilde{i}} r_{i,N} - (a - 1)$. Relative to d_N^* , the design d_{N+1}^* is found by increasing the replication of treatment \tilde{i} by a , and decreasing the total replication for all other treatments by $a - 1$. This implies adding a replicates to \tilde{i} and removing a total of $(a - 1)$ replicates from the other treatments decreases $\sum_i \frac{h_i^2}{r_{i,N+1}}$ more than adding one replicate to treatment \tilde{i} and maintaining the same replication sum for the other $t - 1$ treatments. Following the same logic, d_N^* is improved by adding $a - 1$ replicates to treatment \tilde{i} and, in some fashion, removing $a - 1$ replicates from among the other $t - 1$ treatments. This contradicts the fact that d_N^* is $c_{\mathcal{E}}$ -optimal.

3 Elfving Theorem for the Quadratic Model

The proofs in this section follow from Chapter 2 of Pukelsheim (2006) and concern c -optimality, not $c_{\mathcal{E}}$ -optimality. For the one-factor quadratic polynomial model with $x_i \in [-1, 1]$ the model is,

$$y_i = \tau_0 + \tau_1 x_i + \tau_{11} x_i^2 + e_i = \mathbf{x}_i^T \boldsymbol{\tau} + e_i .$$

The regression range \mathcal{X} is comprised of all vectors $(1, x_i, x_i^2)$. The Elfving set $\mathcal{R} = \text{conv}(\mathcal{X} \cup -\mathcal{X})$ is the convex hull of the set $\mathcal{X} \cup -\mathcal{X}$ where $-\mathcal{X}$ multiplies all vectors in \mathcal{X} by -1 . A coefficient vector, \mathbf{h} , for an estimable function $\mathbf{h}^T \boldsymbol{\tau}$ can be constructed using a linear combination of vectors in \mathcal{R} . Each coefficient vector requires multiplication by a scaling factor to lie on the boundary of \mathcal{R} . The minimum variance for $\widehat{\mathbf{h}^T \boldsymbol{\tau}}$, with respect to an approximate design, is the square of the scaling factor. The coefficient vector for the linear term τ_1 , $\mathbf{h}^T = (0, 1, 0)$, defines a supporting hyperplane to \mathcal{R} and so must lie on its boundary. Hence the minimum variance of $\hat{\tau}_1$ is 1 in terms of the approximate design. The variance in terms of its corresponding exact design is then $1/N$. The approximate c -optimal design, written as proportions of N , is represented by

$$\xi = \left\{ \begin{array}{cc} -1 & 1 \\ 0.5 & 0.5 \end{array} \right\} ,$$

where ± 1 are the two x_i in the design and are equally-replicated $0.5N$ times. Clearly this design will be unable to estimate the quadratic effects and so cannot be $c_{\mathcal{E}}$ -optimal.

The quadratic term has coefficient vector $\mathbf{h}^T = (0, 0, 1)$, which does not lie on the boundary of \mathcal{R} . However, $(0, 0, \frac{1}{2})$ is on the boundary since it intersects the supporting hyperplane defined by $\mathbf{v}^T = (-1, 0, 2)$. Hence, scaling \mathcal{R} by 2 puts this \mathbf{h} on the boundary. The approximate design's minimum variance for the quadratic term is $2^2 = 4$ so the exact design's variance is $4/N$. The approximate c -optimal design is the three-point design

$$\xi = \left\{ \begin{array}{ccc} 0 & -1 & 1 \\ 0.5 & 0.25 & 0.25 \end{array} \right\} .$$

This design can also estimate τ_1 and so is also $c_{\mathcal{E}}$ -optimal.

If we added an additional factor, $u_i \in [-1, 1]$, and include its main and quadratic effect as well as its interaction effect with x and u , the previous minimum variances for the main effect and quadratic terms remain the same in x , with $u_i = 0$. Any number of factors could be added to the model in this manner, establishing the c -optimality of the main effect and quadratic effect for the larger models.

Concerning c -optimality for the two-factor interaction we need only consider the two-factor model

$$y_i = \tau_0 + \tau_1 x_i + \tau_2 u_i + \tau_{12} x_i u_i + \tau_{11} x_i^2 + \tau_{22} u_i^2 + e_i = \mathbf{x}_i^T \boldsymbol{\tau} + e_i .$$

The coefficient vector for τ_{12} is $\mathbf{h}^T = (0, 0, 0, 1, 0, 0)$ which is a supporting hyperplane for the Elfving set and so shares the same minimum variance as the main effects. Its approximate c -optimal design, with supports expressed as coordinates (x_i, u_i) , is

$$\xi = \left\{ \begin{array}{cccc} (-1, -1) & (-1, 1) & (1, -1) & (1, 1) \\ 0.25 & 0.25 & 0.25 & 0.25 \end{array} \right\} .$$

This design will be simultaneously c -optimal for τ_1 and τ_2 , but is clearly unable to estimate the quadratic effects. Hence it fails to be $c_{\mathcal{E}}$ -optimal.

References

Pukelsheim, F. (2006), *Optimal Design of Experiments*, SIAM.